

# NEWTON

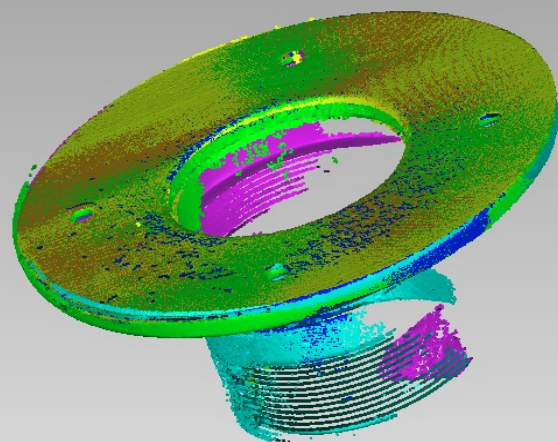
## Underwater Laser Scanner M310UW



Underwater Laser Scanners that capture sub-millimeter measurement for underwater metrology.

### Product Details

- Depth rated up to 100m
- ROV/AUV mounted or cable served
- Only requires GigEthernet and 24VDC from the ROV/AUV
- Live camera view allows operator to achieve maximum productivity
- Captures data up to 5 meters from target
- Combine multiple scans into comprehensive CAD model



Depth of Field (Distance to Object)	Field of View Width—Height	Approximate CAD Model Accuracy
0.5 m	0.42m x 0.55m	0.02 mm
1 m	0.85m x 1.1m	0.05 mm
1.5 m	1.27m x 1.66m	0.11 mm
3 m	2.54m x 3.31m	0.43 mm
4 m	3.39m x 4.42m	0.77 mm
5 m	4.24m x 5.52m	1.20 mm

Above—Combine multiple scans for composite 3D analysis.

Accuracy statements on left are based on post processing of scanner's raw point cloud data. Scanning conditions can effect the raw data acquisition, but post process can be used to filter out noise in the data.



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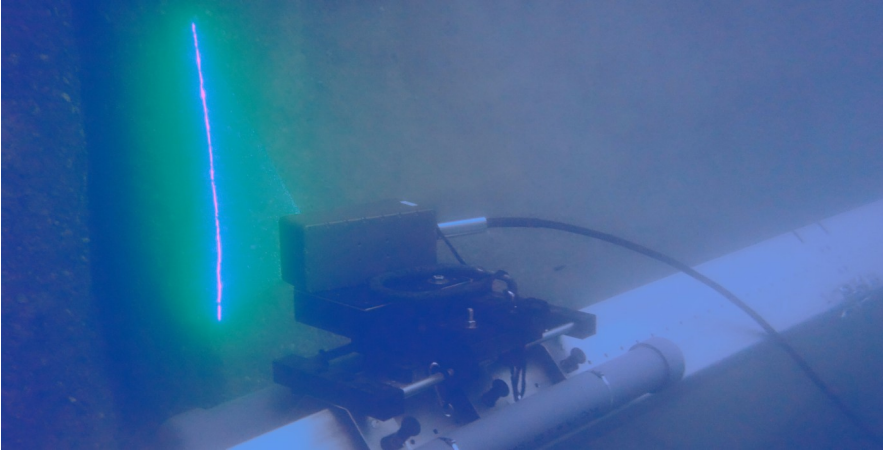
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## Underwater Laser Scanning - M310UW

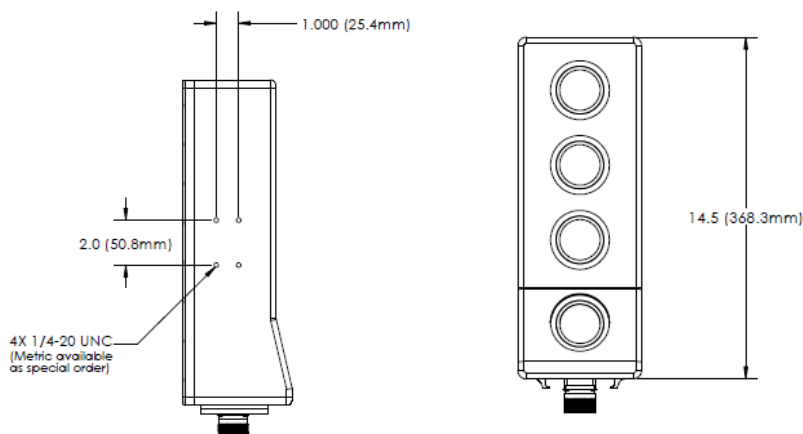
Underwater Laser Scanning exceeds traditional underwater measurements by capturing as built point cloud data with sub-millimeter accuracy. The data captured by the Newton underwater laser scanners leaves asset managers and engineers with absolute confidence in their measurement data.



### Newton Scanner Operation

- **The Newton scanners operate by triangulation** - The laser sweeps the target and the high resolution camera records any deformation of the beam as a point cloud.
- **The scanners scans a target** as distant as 5m and as close as 0.5m, for a scan coverage area up to 4.24 m X 5.54 m. The system measures underwater targets up to an accuracy of 0.02 mm\* (see front).
- **Scanner software can capture much larger target areas** by combining several point clouds together in post processing to form larger composites.
- **Operators may select from several levels of scan quality.** The shortest, coarse scan takes 15 seconds; the longest and most detailed takes about three minutes
- **For visual observation,** the LED ring arrays illuminates the area and the camera transmits an image to the control console screen.
- **Deployment of the scanner head** is designed for fixed, diver or ROV/AUV deployment and has simple mounting holes on the back panel .
- **Pipeline scans** can be taken by fixing the laser line and relying on the motion of the ROVAUV.

### Product Dimensions



### Technical Specifications:

Measurement Range	Between 1m and 5m
Power Requirements	Power 110 to 240 50/60 Hz VAC to the Control Unit (the Control Unit provide power to the sensor)  Requires 24v at 3amps and Gig Ethernet for ROV/AUV Deployment
Cable	Custom for ROV 30m Standard Up to 100m Available
Weight	M310UW- 25lbs in air, 15 lbs in water
Scanner Head Dimensions	241.3 mm x 381 mm x 571.5 mm
Control Unit Dimensions	24.60" x 19.70" x 11.70" (62.5 x 50 x 29.7 cm)  Laptop Option Available
Control Unit Weight	56 lbs (25 kg)  Laptop Option Available
Display	19" (48 cm) Color
Depth Rating	100m

### About Newton Labs

Newton Labs is a Seattle area-based privately held developer and manufacturer of laser scanners, machine vision and robotic systems. Newton's powerful, easy to use, and industrially rugged systems provide solutions for wide ranging applications in many sectors, including aerospace, automotive, bottling, electronics, medical, packaging, and nuclear, among others. In more than 20 years Newton has deployed more than 30,000 machine vision and automaton systems worldwide, many that are first-of-a-kind.