

LDQCWシリーズ ダイオードレーザ駆動電源 取扱説明書



LDQCW-250-XX-YY-ZZ (Rev 5)

LDQCW-600-XX-YY-ZZ (Rev 5)

XX= Ioutmax YY = Maximum Compliance Voltage

ZZ = Max Pulse Width in usec

Warning – Voltage Compliance Requirement

Each LDQCW is custom configured to deliver pulses of current into an array requiring a predefined compliance voltage. The LDQCW will not operate properly when connected to an array that requires more than +105% or less than 75% of the rated voltage of the unit. See the Serial Number label of the unit for the compliance voltage rating. When driving a load requiring more than 105% of the rated voltage of the unit, output current will not reach the programmed value. When driving a load requiring a voltage less than 75% of the specified output voltage, the unit will shut off to protect internal circuitry from over-temperature conditions (see Pin 7 of the Interface)

Warning – Output Floating

The output of the LDQCW is floating and therefore, neither side of the laser diode may be connected to the same ground as signal ground (Program, Monitor).



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<http://www.optoscience.com>

東京本社 〒160-0014 東京都新宿区内藤町1番地 内藤町ビルディング
TEL:03(3356)1064 FAX:03(3356)3466 E-mail:info@optoscience.com
大阪支店 〒532-0011 大阪市淀川区西中島7-7-2 新大阪ビル西館
TEL:06(6305)2064 FAX:06(6305)1030 E-mail:osk@optoscience.com
名古屋営業所 〒450-0002 名古屋市中村区名駅2-37-21 東海ソフトビル
TEL:052(569)6064 FAX:052(569)8064 E-mail:ngo@optoscience.com

I. Overview of LDQCW System

Lumina Power's LDQCW power supplies are designed for pulsing diode lasers in Quasi-CW applications. Before operating this unit, it is important to understand the operation. A block diagram of the power supply is shown below.

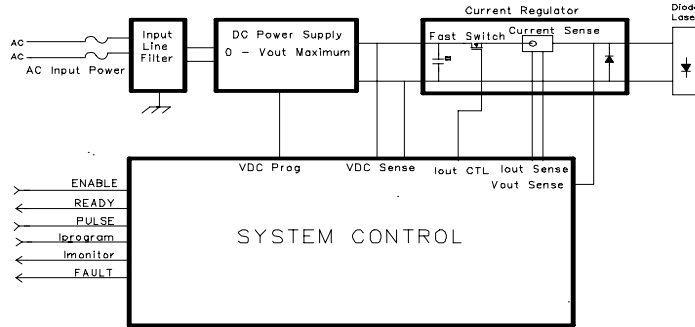


Figure 1
LDQCW Block Diagram

Referring to Figure 2, it's easiest to think of the basic elements of the system as a high power linear regulator. The four main components are:

- A **DC input voltage** which is applied to the input of the regulator
- A **high power linear regulator** which is controlled by an error signal
- A **high current Hall-Effect current monitor**
- **Control system**

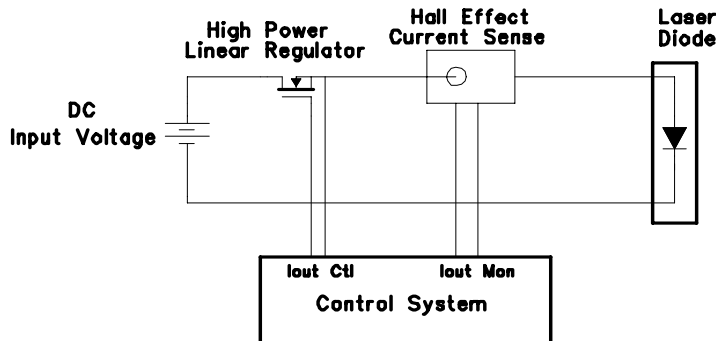


Figure 2
Simplified LDQCW Block Diagram

The **DC input voltage** is, in fact, a sophisticated high frequency switchmode power supply which includes power factor correction, a soft switching inverter, an input line filter and various protection circuits.

The **high power linear** regulator is typically a bank of high power MOSFETS mounted on an appropriate heat sink with over-temp protection.

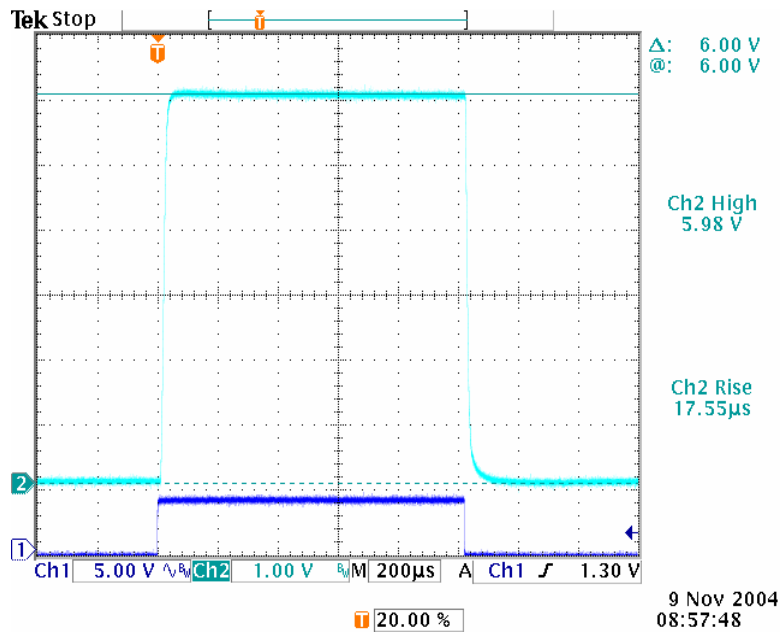
The **high current Hall Effect current monitor** provides a fast, low loss method to measure high current pulses.

II. Pulsing Characteristics

The rise and fall times of LDQCW pulses are a compromise between speed and minimization of overshoot. Figure 3 shows a typical rise time for an LDQCW.

Figure 3
Typical Rise/Fall Time

This waveform shows a rise/fall time of less than 20usec.

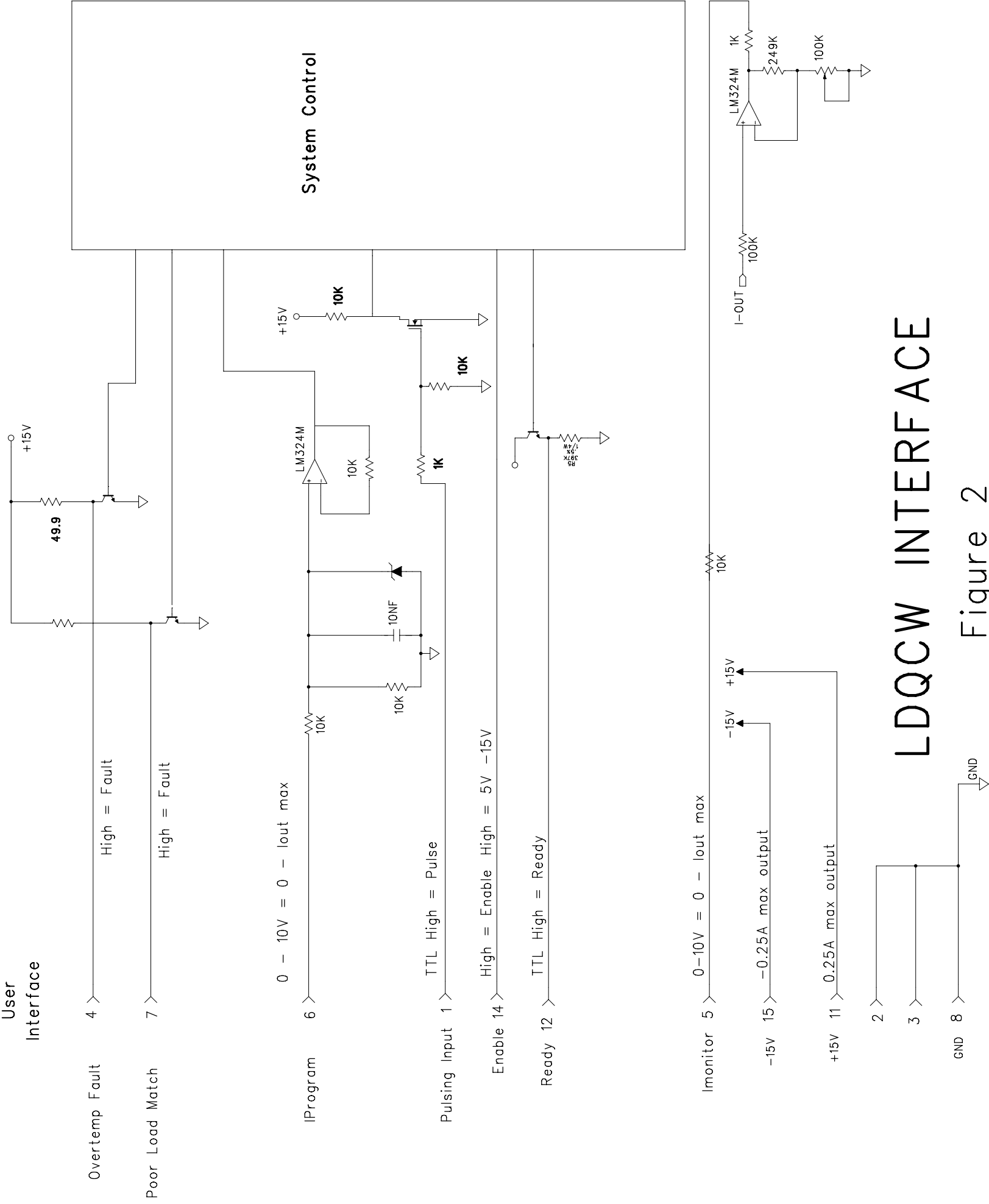


III. Operation of the LDQCW

The programming, monitoring and control functions LDQCW Interface as shown below.

LDQCW-250/600-XX-YY Interface Connector Type: 15 pin D-sub Female

Pin	Description
1	Pulsing Input: (Input, TTL) This signal is a TTL input for pulsing the system. System delivers pulses of current with output current levels as programmed on Pin 6
2,3,8	GND
4	Temp Fault: (Output, TTL) When the internal temperature on main heat sink has exceeded a safe operating temperature, the output is disabled and this fault is transmitted. Temp Fault output is TTL high.
5	Iout Monitor: (Output) 0 – 10V = Ioutmax
6	Iprogram(+): (Input) 0 - 10V = Ioutmax
7	Poor load match: (Output, TTL) When the voltage compliance of the diode laser load is not within 80% to 100% of the maximum rated voltage compliance of the unit, the output is disabled and this fault is transmitted. This fault may be reset three times. If the fault persists after three resets, the unit will disable the output until AC power is removed and applied again. Fault output is TTL high.
11	+15V @0.25A (output) Auxiliary +15V power supply for user. Up to +0.25A output current available.
12	Ready Status: (Output, TTL) When the system has been Enabled and no faults are present, this signal is transmitted. When system is ready, signal is a TTL high.
13	No connection
14	Enable: (Input, TTL) A TTL high level signal enables system operation. The Enable is a soft start system turn on and should not be used for pulsing. If the system is free of faults and the interlock pin is grounded, a Ready Status high signal is transmitted and system is ready to pulse.
15	-15V @0.25A (output) Auxiliary -15V power supply for user. Up to –0.25A output current available.



LDQCW INTERFACE

Figure 2

Operation of the LDQCW

Warning – Voltage Compliance Requirement

Each LDQCW is custom configured to deliver pulses of current into an array requiring a predefined compliance voltage. The LDQCW will not operate properly when connected to an array that requires more than +100% or less than 80% of the rated voltage of the unit. See the Serial Number label of the unit for the compliance voltage rating. When driving a load requiring more than 100% of the rated voltage of the unit, output current will not reach the programmed value. When driving a load requiring a voltage less than 80% of the specified output voltage, the unit will shut off to protect internal circuitry from over-temperature conditions (see Pin 7 of the Interface)

Warning – Output Floating

The output of the LDQCW is floating and therefore, neither side of the laser diode may be connected to the same ground as signal ground (Program, Monitor).

1. Connect diode laser load to power supply. A custom strip line cable has been supplied to minimize inductance. Please note the cable is marked with (+) and (-) labels.
2. Connect appropriate interface to LDQCW Interface Connector. Make sure **Iprogram(+)**, pin 6, is set to 0.0V.
3. Connect AC input power cables. **Make sure AC input power is OFF.** LDQCW models accept input voltage between 90-264VAC.
4. Apply AC input power to unit. After a few seconds the cooling fan should begin to operate.
5. Set **Iprogram(+)**, Pin 6 of the interface connector, This signal is the 0-10V program which will program the output current level. Calibration is set so that $10V = 0 - I_{out_{max}}$.
6. **Enable** the output by applying a TTL level high signal to pin 14 of the interface connector. The **Enable** control checks for faults and prepares the system for pulsing.
7. Pulse the unit via the **Pulsing Input** control, pin 1. Maximum pulse widths should not be greater than 1msec. The amplitude of the pulses will be determined via the analog **Iprogram(+)** signal. Maximum average power delivered to the load should be less than the rated power capability of the unit.

IV. Unit Faults

The unit is designed to monitor various faults such as

- **Temp Fault: (Output, TTL, Pin 4)** When the temperature of the internal heat sink has exceeded a safe operating level, the system is shut off and this fault is transmitted. Fault output is TTL high. Fault can be cleared by setting the **Enable**, pin 14, to TTL low and then high.

- **Poor load match: (Output, TTL, Pin 7)** When the voltage compliance of the diode laser load is below 75% of the specified compliance voltage of the unit, the output is disabled and this fault is transmitted. Fault output is TTL high. This fault may be cleared via the **Enable** signal three times. If the fault persists after three resets, the unit will disable the output until AC power is removed and applied again.



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東京本社 〒160-0014 東京都新宿区内藤町1番地 内藤町ビルディング
TEL:03(3356)1064 FAX:03(3356)3466 E-mail:info@optoscience.com
大阪支店 〒532-0011 大阪市淀川区西中島7-7-2 新大阪ビル西館
TEL:06(6305)2064 FAX:06(6305)1030 E-mail:osk@optoscience.com
名古屋営業所 〒450-0002 名古屋市中村区名駅2-37-21 東海ソフトビル
TEL:052(569)6064 FAX:052(569)8064 E-mail:ngo@optoscience.com